

# Maschinenprüfplattform: Rollover stability of agricultural machines

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- $\circ$  Introduction
- Rollover stability model
- $\circ$  Stability test-rig
- Stability test-rig test
- Conclusions and Future Works



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 The Italian National Institute for Insurance Against Accidents at Work (INAIL) recorded:



 $\,\circ\,$  Many incidents go unrecorded or are inaccurately and incompletely reported.

 $_{\odot}$  Similar trends have been observed in Switzerland and Austria.

## Introduction

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Types of ROPS fitted on agricultural tractors involved in fatal overturn accidents in Italy during the period 2008-2014 (Pessina et al., 2015).

- Old and worn tractors, often lacking Rollover Protective Structures (ROPS) and seat belts, contribute significantly to fatal accidents.
- Even when ROPS are present, they are frequently either removed or left in the rest position.
- Understanding the stability behaviour of machines operating on slopes is crucial for accident prevention.



## Rollover stability model

- Simplified tractor **kinematic and dynamic models** of the tractor (i.e., wheels as rigid bodies).
- Used to compute the tractor configuration and thus the position of the four wheel-terrain contact points.
- Computation of the wheel-ground contact forces as the tilting angle changes.
- The **instability** is detected as soon as at least **one of the contact forces becomes null or negative**.
- **Experimental test** on real machine are needed to tune and evaluate the model.



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Stability test-rig

- **Tilting** and **rotating supporting plane** to orientate a tested machines in any direction.
- Support plane divided in 4 plates (i.e., each one supports one wheel).
  - Each plate can move up and down independently to simulate **bumps or potholes**.
  - Each plate integrates a series of load cells to measure the wheel-terrain contact force.
- $\odot$  Support plane covered by a special grid to prevent the tractor sliding during the test.

- $\circ$  Tilting ( $\alpha$ ): up to 55°
- $\circ$  Rotation ( $\beta$ ): ±180°
- Plate vertical displacement: 0÷300mm
- Max testing dimension: 6x4m
- Max testing weight: 10t



#### Indirect measure of the Centre of Gravity (CoG) position.

- $\circ$  Based on the measurement of the 4 components of the contact forces.
- Different orientation of the machine to minimize errors (e.g. fuel displacement inside the tank).







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## Static roll-over stability evaluation

- Different orientations and tractor configurations.
- The result is a rollover stability map.





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#### Static roll-over stability evaluation





Specialized mountain tractor

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Stability analysis in presence of different ground conformations.





1.5

0.5

0

-1

0

-0.5

#### Stability analysis in presence of different ground conformations



-3

-2



Phase I instability

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- – – Phase II instability
  - + Experimental data

Transition phase: when the front axle joint reaches it limit range and goes in contact with the mechanical end-stop, the stability increases.

#### Phase I instability



Pivoting axle joint

### **Phase II instability**



Pivoting axle joint blocked

#### Stability analysis in presence of different ground conformations

 After a certain level of misalignment, the front axle rotations is blocked by the mechanical stop and the tractor behaves as a single rigid body.



#### Stability analysis on tractor following particular path

 $\circ$  e.g., helical path to move to the next row in a terraced orchard/vineyard.



#### **Future works**

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- Experiments with different machine configurations:
  - $\circ~$  Different inflation pressures
  - $\circ$  Double wheel systems
  - Water ballasting
- $\circ$  Experiments with different equipment.
- Improvement of the stability model (wheel as a non-rigid body).
- $\,\circ\,$  Development of rollover warning systems.











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